

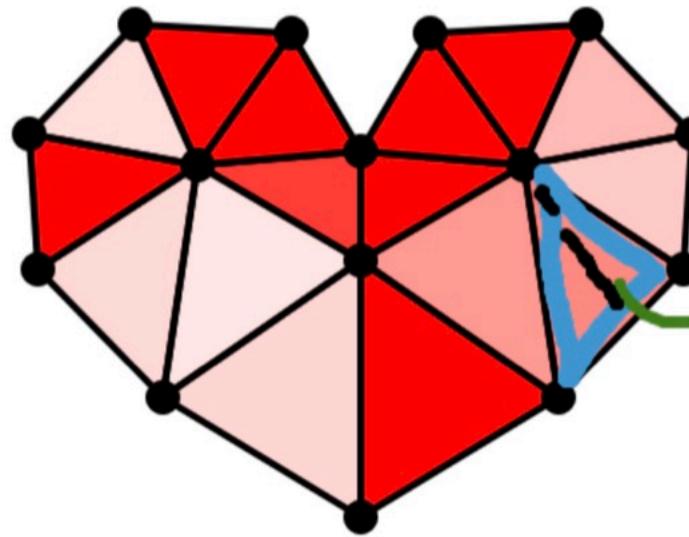
CSCI 461: Computer Graphics

Middlebury College, Spring 2025

Lecture 2A: Linear Algebra (Vectors)

By the end of today's lecture, you will be able to:

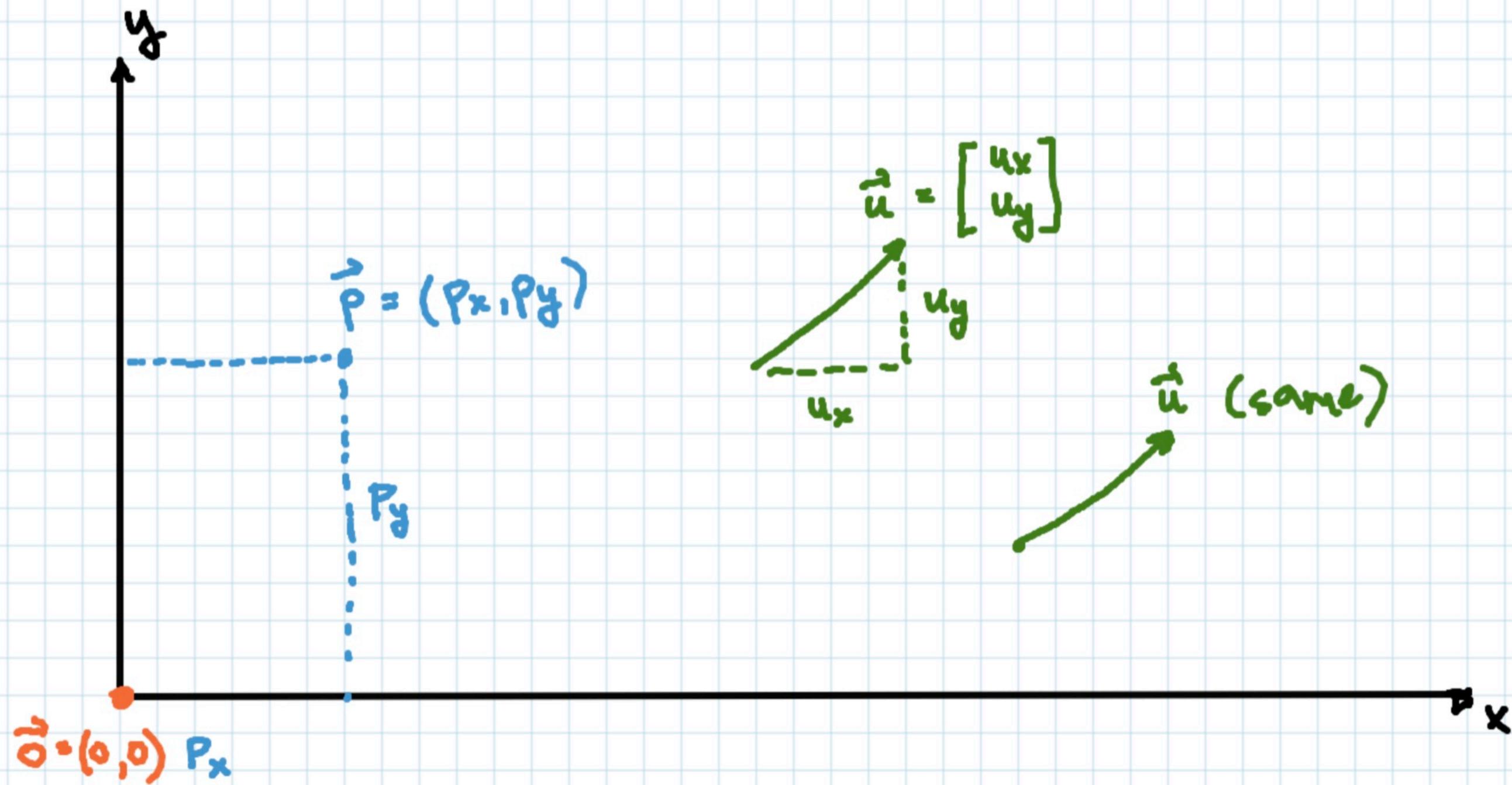
- perform operations on vectors such as **addition**, **subtraction**, **scaling**,
- calculate the **length** of a vector and compute **unit vectors**,
- compute the **dot product** and **cross product** of two vectors,
- calculate the **area** of a triangle using the cross product,
- **represent lines and planes** using vector notation,
- use **glMatrix** to do everything mentioned above.



$$\text{area} = \frac{1}{2} \text{ base} \times \text{height}$$

Building blocks: points and vectors.

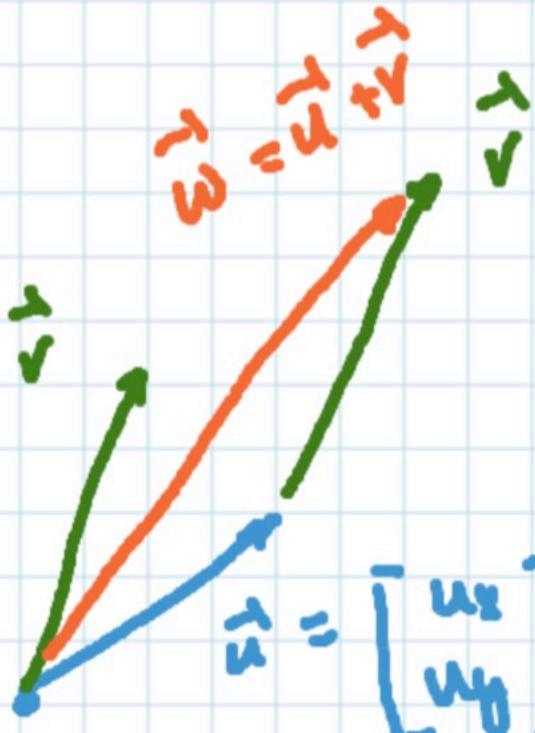
We'll use an arrow on top of symbols to denote points (\vec{p}) and vectors (\vec{u}).



Vector addition, subtraction, scaling, unit vectors.

y 1

$$\vec{w} = \begin{bmatrix} u_x + v_x \\ u_y + v_y \end{bmatrix}$$



scaling

$$z\vec{u} = \begin{bmatrix} z u_x \\ z u_y \end{bmatrix}$$

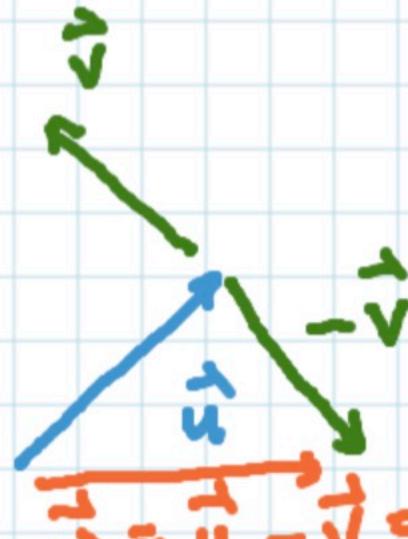


length: vector $\vec{u} \in \mathbb{R}^3$

$$\|\vec{u}\| = \sqrt{u_x^2 + u_y^2 + u_z^2}$$

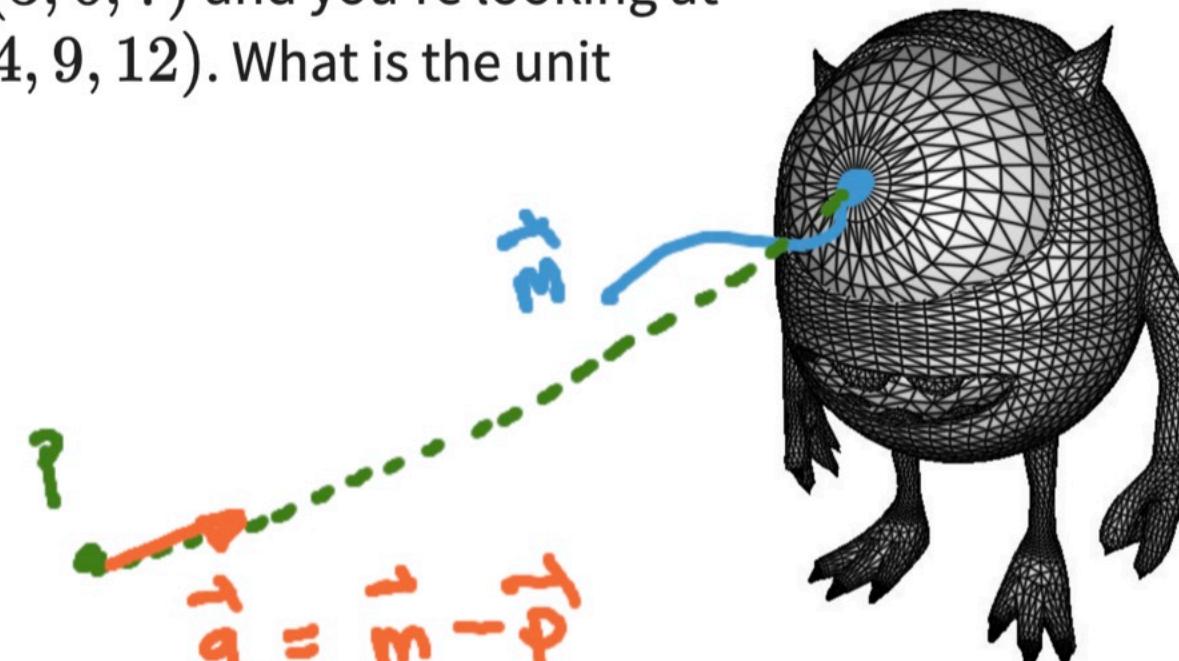
unit vector:
(length = 1)

$$\frac{\vec{u}}{\|\vec{u}\|}$$



Example: calculating a unit gaze direction.

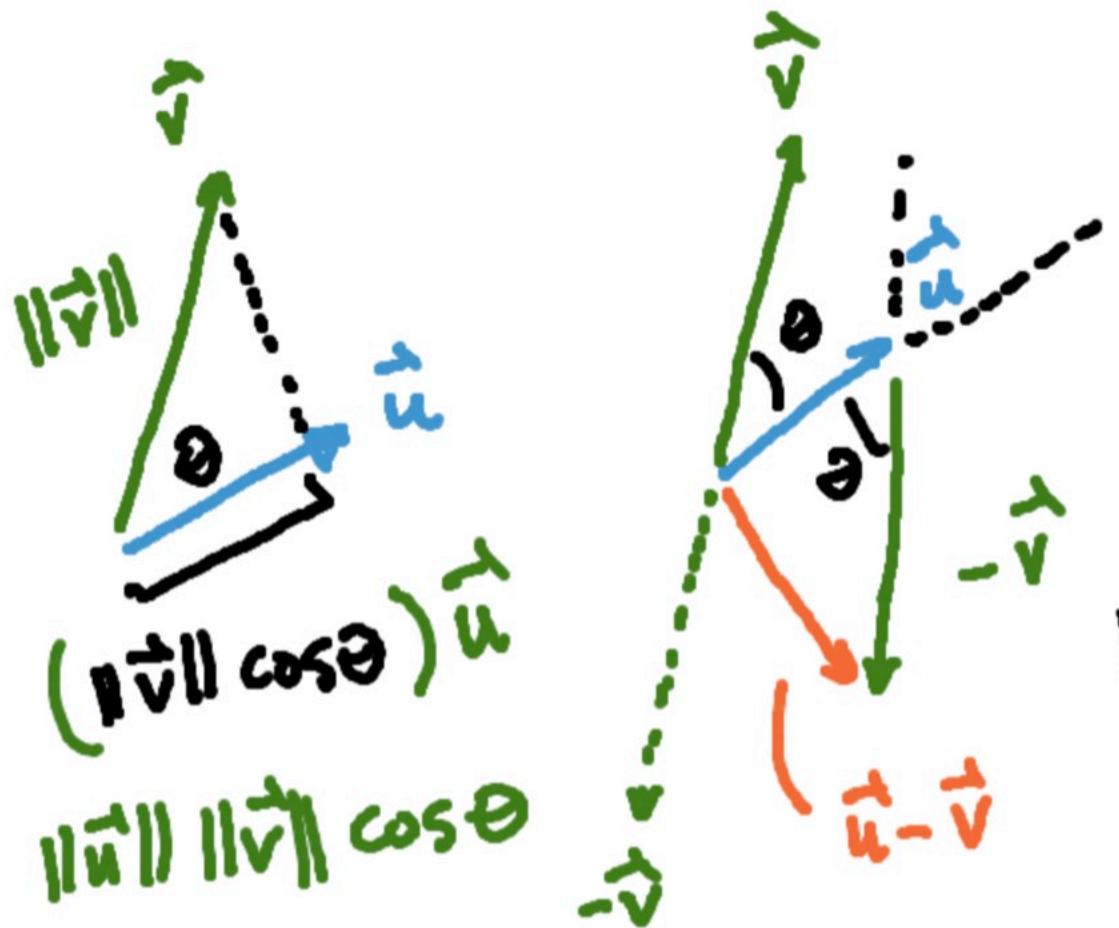
Imagine you're standing at a point $\vec{p} = (3, 6, 7)$ and you're looking at Mike Wazowski who is located at $\vec{m} = (4, 9, 12)$. What is the unit vector pointing in the direction of Mike?



$$\hat{g} = \frac{\vec{m} - \vec{p}}{\|\vec{m} - \vec{p}\|}$$

$$\begin{aligned}\hat{g} &= \frac{\begin{bmatrix} 4 \\ 9 \\ 12 \end{bmatrix} - \begin{bmatrix} 3 \\ 6 \\ 7 \end{bmatrix}}{\|\dots\|} = \frac{\begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}}{\|\dots\|} = \frac{\begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}}{\sqrt{1^2 + 3^2 + 5^2}} = \frac{\begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}}{\sqrt{35}}\end{aligned}$$

Derivation of dot product in relation to angles. $\vec{c}^2 = \vec{a}^2 + \vec{b}^2 - 2\vec{a}\vec{b} \cos \alpha$



$$\text{if } \theta = 90^\circ (\pi/2)$$

$\vec{u} \cdot \vec{v} = 0$ perpendicular/orthogonal.

cosine law

$$||\vec{u} - \vec{v}||^2 = ||\vec{u}||^2 + ||\vec{v}||^2 - 2||\vec{u}|| ||\vec{v}|| \cos \theta$$

$$\begin{aligned} ||\vec{u}||^2 + ||\vec{v}||^2 &= ||\vec{u}||^2 + ||\vec{v}||^2 - 2||\vec{u}|| ||\vec{v}|| \cos \theta \\ -2u_x v_x & \\ -2u_y v_y & \\ -2u_z v_z & \end{aligned}$$

$$u_x v_x + u_y v_y + u_z v_z = ||\vec{u}|| ||\vec{v}|| \cos \theta$$

dot product

$$\vec{u} \cdot \vec{v} = \sum_i u_i v_i = ||\vec{u}|| ||\vec{v}|| \cos \theta$$



Definition of the cross product.

$$\hat{v} = \begin{bmatrix} v_x \\ v_y \\ v_z \end{bmatrix}$$

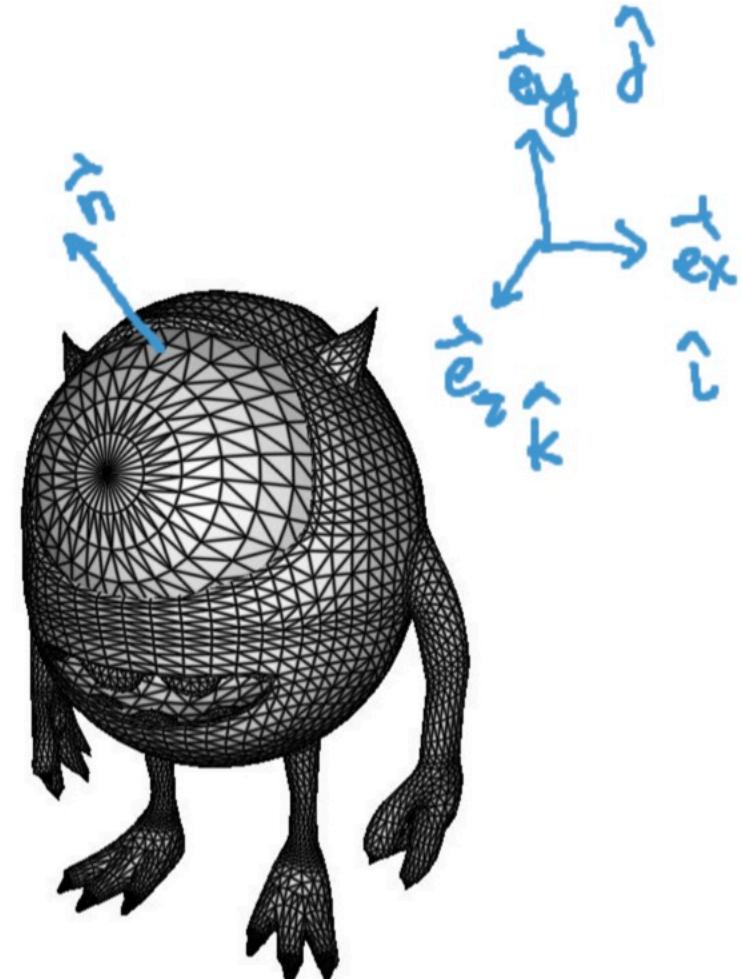
\perp perpendicular.

$$\begin{aligned}\vec{u} \times \vec{v} &= (u_y v_z - u_z v_y) \hat{e}_x \\ &\quad - (u_x v_z - u_z v_x) \hat{e}_y \\ &\quad + (u_x v_y - u_y v_x) \hat{e}_z\end{aligned}$$

order matters!

$$\text{area of a triangle} = \frac{1}{2} \| \vec{u} \times \vec{v} \|$$

$$\begin{aligned}\vec{v} &= \vec{c} - \vec{a} \\ \vec{u} &= \vec{b} - \vec{a} \\ \vec{n} &= \vec{u} \times \vec{v}\end{aligned}$$



Exercise: show that $\vec{u} \cdot (\vec{u} \times \vec{v}) = 0$.

$$\vec{u} \times \vec{v} = (u_y v_z - u_z v_y) \vec{e}_x - (u_x v_z - u_z v_x) \vec{e}_y + (u_x v_y - u_y v_x) \vec{e}_z$$

Use:

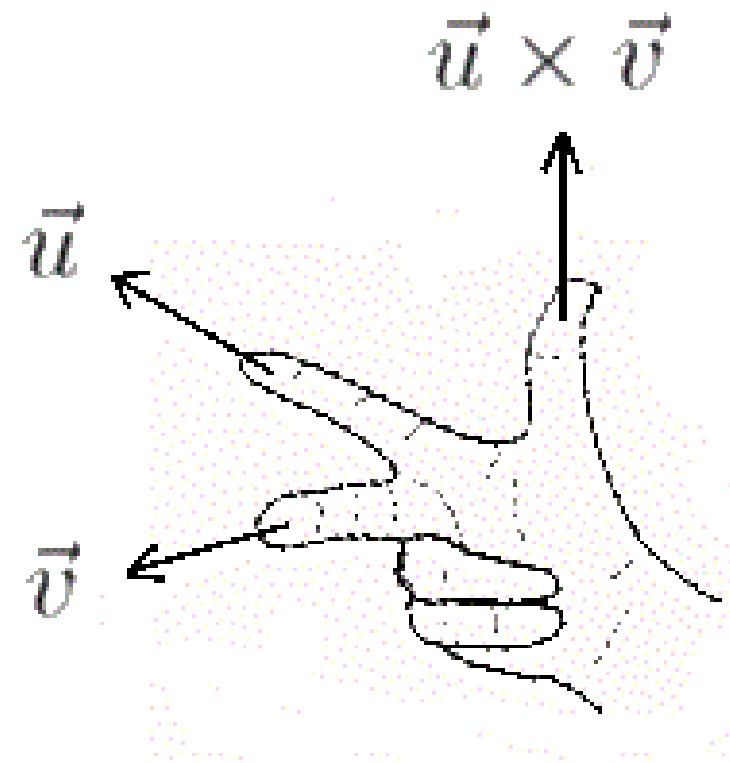
$$\vec{u} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \quad \vec{v} = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}$$

Solution: first we calculate $\vec{u} \times \vec{v} = \begin{bmatrix} 12 - 15 \\ -(6 - 12) \\ 5 - 8 \end{bmatrix} = \begin{bmatrix} -3 \\ 6 \\ -3 \end{bmatrix}$.

Then verify $\vec{u} \cdot (\vec{u} \times \vec{v}) = (1)(-3) + (2)(6) + (3)(-3) = -3 + 12 - 9 = 0$.

Visualizing the cross product.

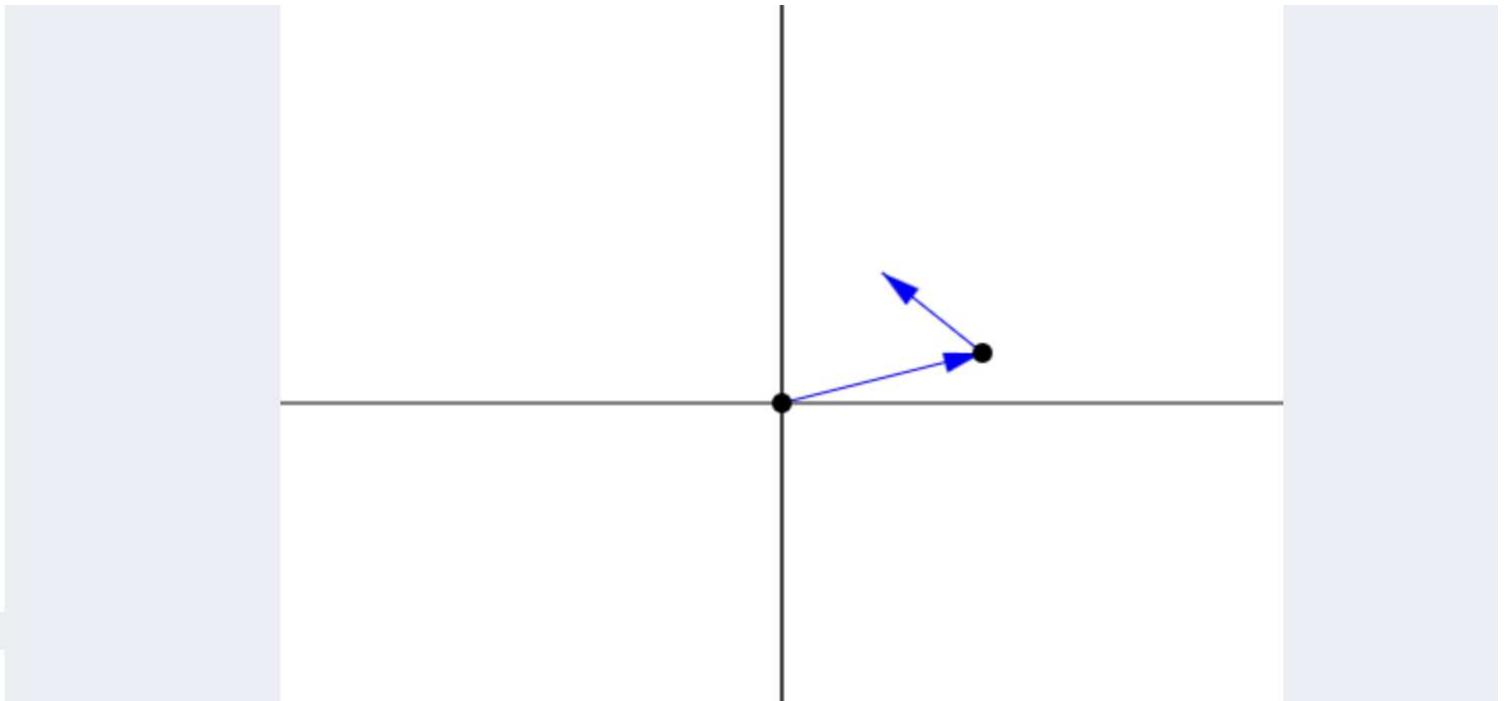
Using **RIGHT** hand: align index finger with \vec{u} , then align middle finger (or all other fingers) with \vec{v} (moving towards your palm). Thumb will point in direction of $\vec{u} \times \vec{v}$.



Exercises: using glMatrix.

Look up documentation at: <https://glmatrix.net/docs/>.

```
1  const origin = vec2.fromValues(0, 0);
2  const u = vec2.fromValues(100, 25);
3  const v = vec2.fromValues(-50, 40);
4
5  const x0 = vec2.add(vec2.create(), origin, u);
6
7  // array of points to plot as dots
8  let points = [origin, x0];
9
10 // array of vectors to plot
11 let vectors = [u, v];
12
13 // array of vector tails (optional)
14 // set an entry to 'undefined' to use the origin
15 let tails = [undefined, points[1]];
16
17
```

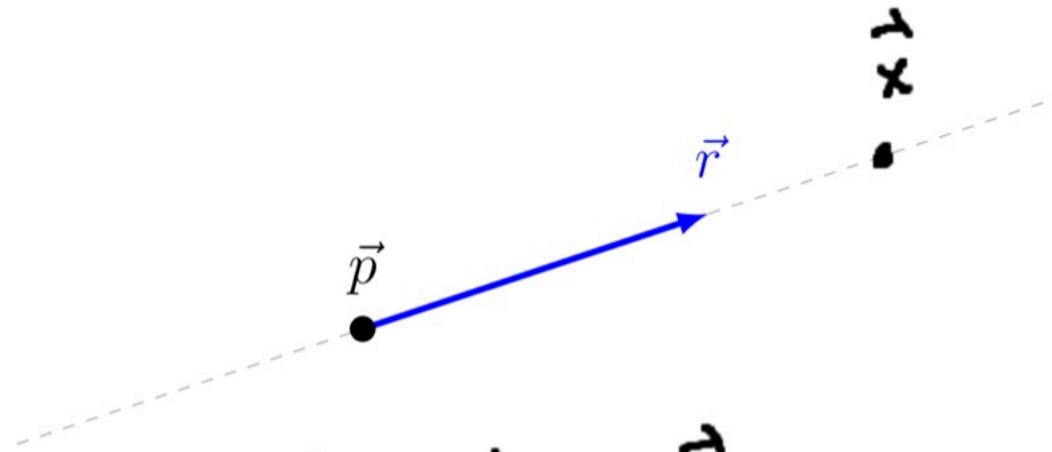


- Calculate and visualize the vector $\vec{w}_1 = \vec{u} + \vec{v}$. Use `console.log` to print the result, and verify (on paper).
- Calculate and plot $\vec{x}_1 = \vec{x}_0 + \vec{v}$.
- Visualize $-\vec{v}$.
- Calculate and visualize the vector $\vec{w}_2 = \vec{u} - \vec{v}$.
- Calculate the length $\ell = \|\vec{w}_2\|$ and use `console.log` to print the result.
- Normalize \vec{w}_2 to produce $\vec{w}_3 = \frac{1}{\ell}\vec{w}_2$.
- Use \vec{w}_3 to plot the end of the vector $\vec{u} - \vec{v}$ using `vec2.scaleAndAdd``.
- Calculate and visualize a vector perpendicular to \vec{w}_1 and use `.dot` to verify the vector is indeed perpendicular to \vec{w}_1 (use `console.log` to print the result).

Possible implementation.

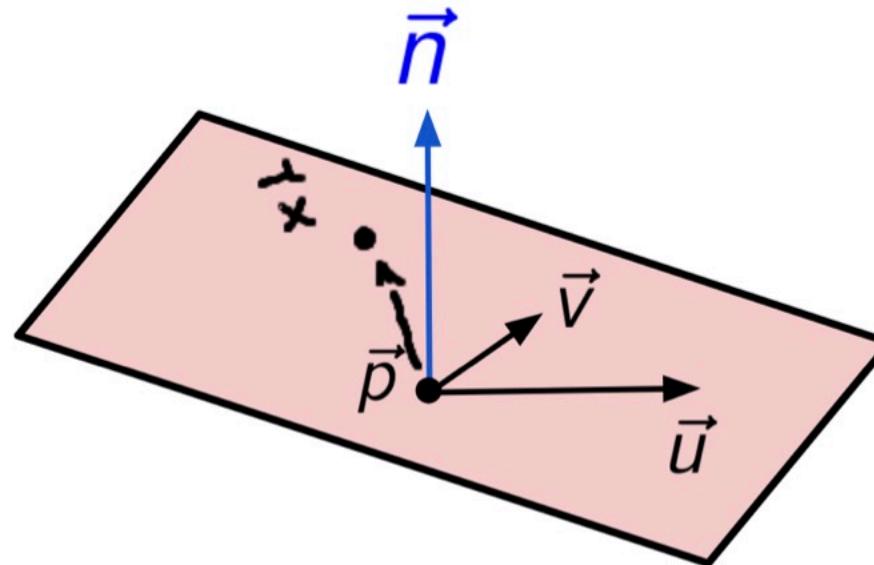
```
1 const origin = vec2.fromValues(0, 0);
2 const u = vec2.fromValues(100, 25);
3 const v = vec2.fromValues(-50, 40);
4
5 const x0 = vec2.add(vec2.create(), origin, u);
6
7 const w1 = vec2.add(vec2.create(), u, v);
8 const x1 = vec2.add(vec2.create(), x0, v);
9 const mv = vec2.negate(vec2.create(), v);
10 const w2 = vec2.subtract(vec2.create(), u, v);
11
12 const l = vec2.length(w2);
13 console.log(l);
14 const w3 = vec2.normalize(vec2.create(), w2);
15 console.log(w3);
16 console.log(vec2.scale(vec2.create(), w2, 1.0/l));
17 const x2 = vec2.scaleAndAdd(vec2.create(), origin, w3, l);
18
19 const n = vec3.cross(vec3.create(), vec3.fromValues(0, 0, 1), vec3.fromValues(w1[0], w1[1], 0));
20
21 console.log(vec2.dot(n, w1));
22
23 let points = [origin, x0, x1, x2];
24 let vectors = [u, v, w1, mv, w2, n];
25 let tails = [undefined, points[1], undefined, x0];
```

Representing lines and planes.



$$\vec{x} = \vec{p} + t\vec{r}$$

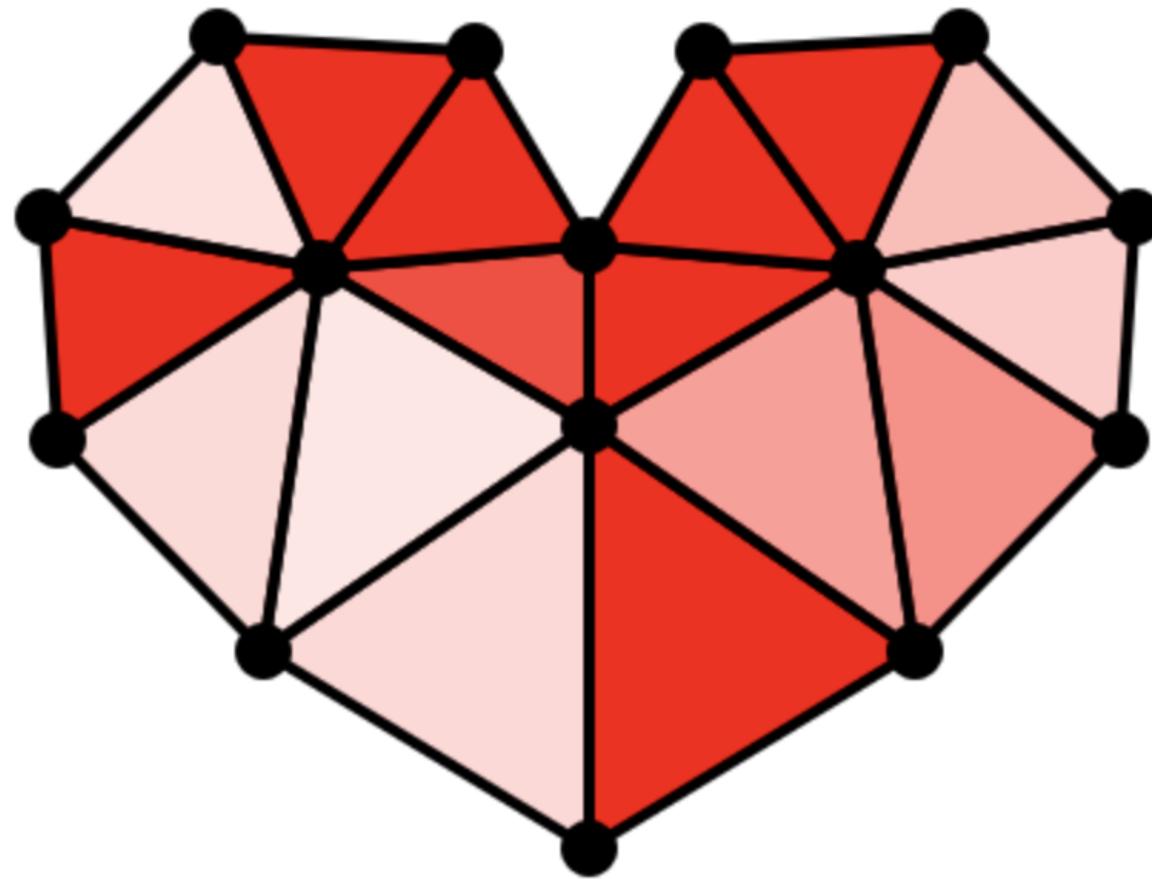
$$t \in \mathbb{R}$$



$$\vec{x} = \vec{p} + s\vec{u} + t\vec{v}$$

$$\vec{n} \cdot (\underbrace{\vec{x} - \vec{p}}_{\text{vector in plane}}) = 0$$

Back to our heart example.



- **Left-half of the room:** find the area of the **left** side of the heart.
- **Right-half of the room:** find the area of the **right** side of the heart.
- Split up the work and add up the result to estimate the *total* area of the heart.
- *Hint:* use the cross product. Hover over the dots in the notes to get triangle vertex coordinates (doesn't need to be exact).

Summary

- Dot product will be useful for calculating diffuse component of lighting model.
- Cross product useful for calculating perpendicular vectors (and areas).
- Intersections useful for figuring out what we can see (and also what is in a shadow).
- Please try out the **example** assignment on the [Setup](#) page.
- **Office hours :** (please come say hi!)
 - Tuesdays: 2pm - 3:30pm
 - Thursdays: 2pm - 3:30pm
 - Fridays: 11am - 12pm
- Next class: **matrices**.